



Safety assurance of automated driving systems. Raising the level of ambition

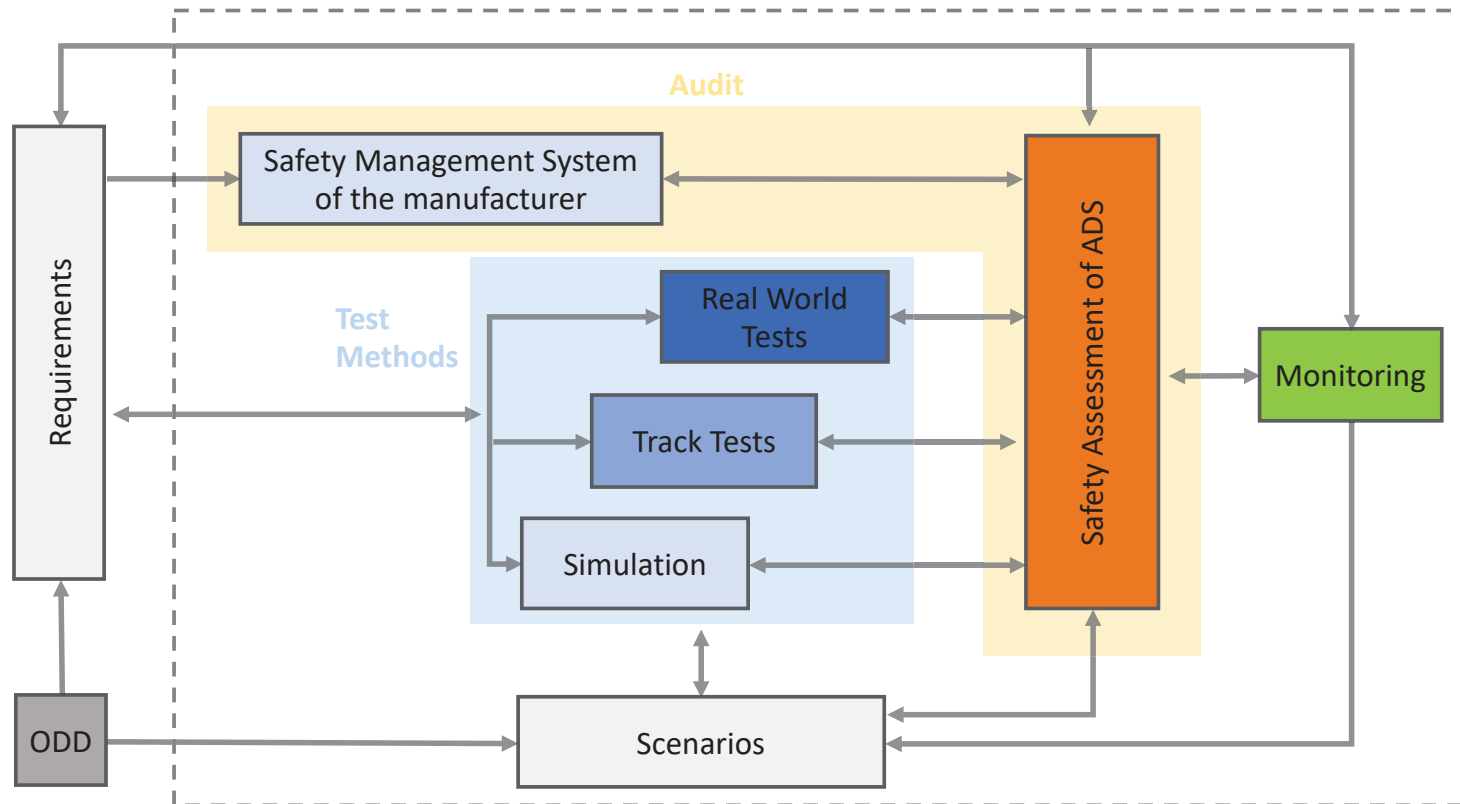
SIP-adus Workshop 2020

12 November 2020

B. Ciuffo, K. Mattas, M.C. Galassi

Joint
Research
Centre

Assessment of ADS safety in GRVA/VMAD*



Example: ALKS Regulation 157

- Requirements. The activated system shall:
 - comply with traffic rules
 - not cause any collisions reasonably foreseeable and preventable

Example: ALKS Regulation 157

- Requirements. The activated system shall:
 - comply with traffic rules **Operational requirement**
 - not cause any collisions reasonably foreseeable and preventable
 - adapt the speed to adjust the distance to a vehicle in front in the same lane to be equal or greater than the minimum following distance.

<i>Present speed of the ALKS vehicle</i>		<i>Minimum time gap</i>	<i>Minimum following distance</i>
(km/h)	(m/s)	(s)	(m)
7.2	2.0	1.0	2.0
10	2.78	1.1	3.1
20	5.56	1.2	6.7
30	8.33	1.3	10.8
40	11.11	1.4	15.6
50	13.89	1.5	20.8
60	16.67	1.6	26.7

Example: ALKS Regulation 157

- Requirements. The activated system shall:
 - comply with traffic rules
 - not cause any collisions reasonably foreseeable and preventable
 - adapt the speed to adjust the distance to a vehicle in front in the same lane to be equal or greater than the minimum following distance.

<i>Present speed of the ALKS vehicle</i>		<i>Minimum time gap</i>	<i>Minimum following distance</i>
(km/h)	(m/s)	(s)	(m)
7.2	2.0	1.0	2.0
10	2.78	1.1	3.1
20	5.56	1.2	6.7
30	8.33	1.3	10.8
40	11.11	1.4	15.6
50	13.89	1.5	20.8
60	16.67	1.6	26.7

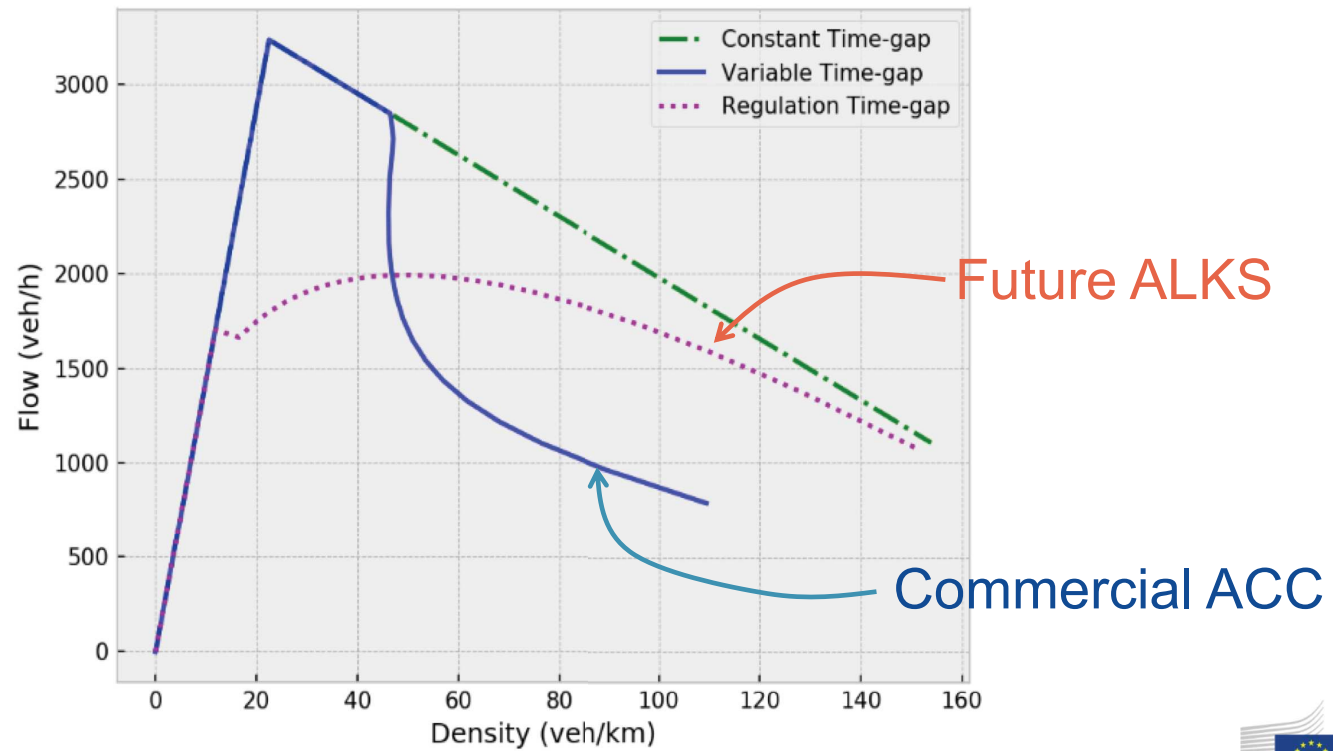
Performance requirement

- avoid a collision with a cutting in vehicle if If the cutting in vehicle is 30 cm inside the lane and

$$TTC > \frac{u_{rel}}{6 * 2} + 0.35 s$$

Effect of operational requirements. Example

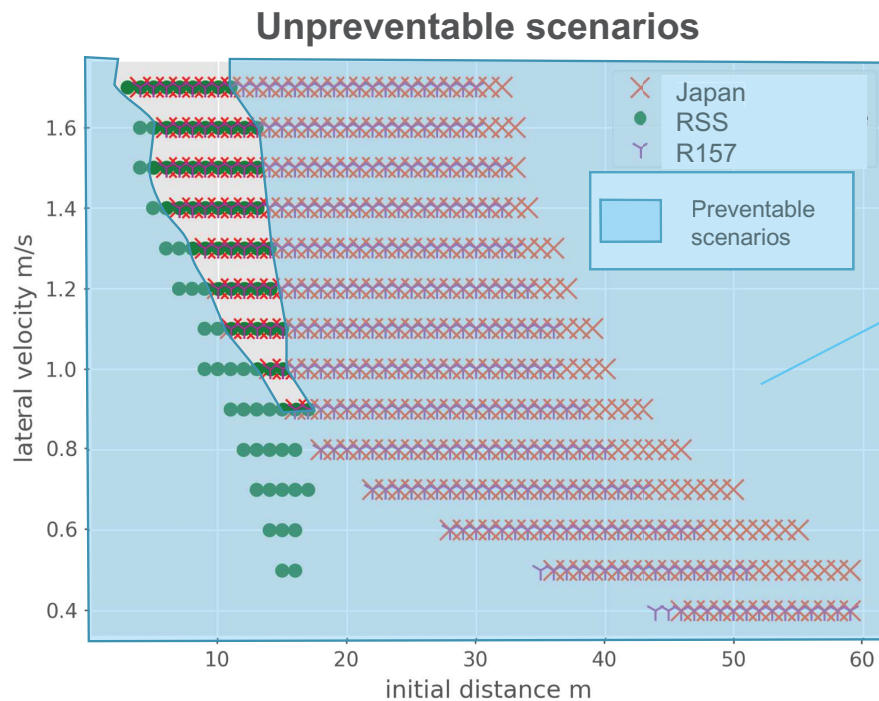
Traffic fundamental diagram



JRC recommendation

- Focus on **performance** rather than behavioural/operational **requirements**
- **Combine different approaches in a transparent way** to set the performance level (human behaviour, technological capability, physical boundaries)
- Adopt a **statistical approach to assess** the requirements (models are not perfect)

Comparison between RSS and VMAD Driver



- **Unpreventable scenarios are those where both the validated driver model and the safety envelope approach produce an accident**
- **An ADS cannot be less safe than a human and shall take advantage of the available technologies**

Conclusions

- Setting operational requirements can induce **negative effects on traffic flow** which are difficult to be foreseen and can **limit technological capability** to improve both safety and traffic efficiency
- Performance requirements have to be set in a **transparent and credible way** to clearly define the level of ambition for future Ads. Different approach can be combined in order to exploit their benefits and cope with their limitations
- Performance requirements should be used to **define accident probability** on the set of scenarios used rather than to define which scenario is preventable
- A safety margin should be used to define **of how much an ADS should be safer** than a human driver supported by state-of-the-art technologies

Thank you



© European Union 2020

Unless otherwise noted the reuse of this presentation is authorised under the [CC BY 4.0](https://creativecommons.org/licenses/by/4.0/) license. For any use or reproduction of elements that are not owned by the EU, permission may need to be sought directly from the respective right holders.

Slide xx: [element concerned](#), source: [e.g. Fotolia.com](#); Slide xx: [element concerned](#), source: [e.g. iStock.com](#)